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In the Claims:

Claims 1-3 (canceled)

Claim 4 (previously presented): An operating system for handling motor vehicle telematic tasks and motor vehicle control tasks, comprising:

an operating system which handles motor vehicle telematic tasks differently than motor vehicle control tasks,

a motor vehicle telematic task being destroyed when it completes in order to free system resources used to perform said motor vehicle telematic task, and

a motor vehicle control task being suspended rather than destroyed when it completes so that it can be reactivated later when required again without rebuilding needed system resources.

Claim 5 (previously presented): The operating system in Claim 4 wherein control tasks that complete are suspended directly by the kernel of the operating system rather than by a software layer above the kernel.

Claim 6. (previously presented): A method of handling motor vehicle telematic tasks and motor vehicle control tasks with a single operating system, comprising the steps of:

placing control tasks into a suspended state when they complete, so that any control task can be reactivated later when required without rebuilding needed system resources; and

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destroying any telematic task when it completes in order to free system resources used to perform said any telematic task.